

FIG. 1

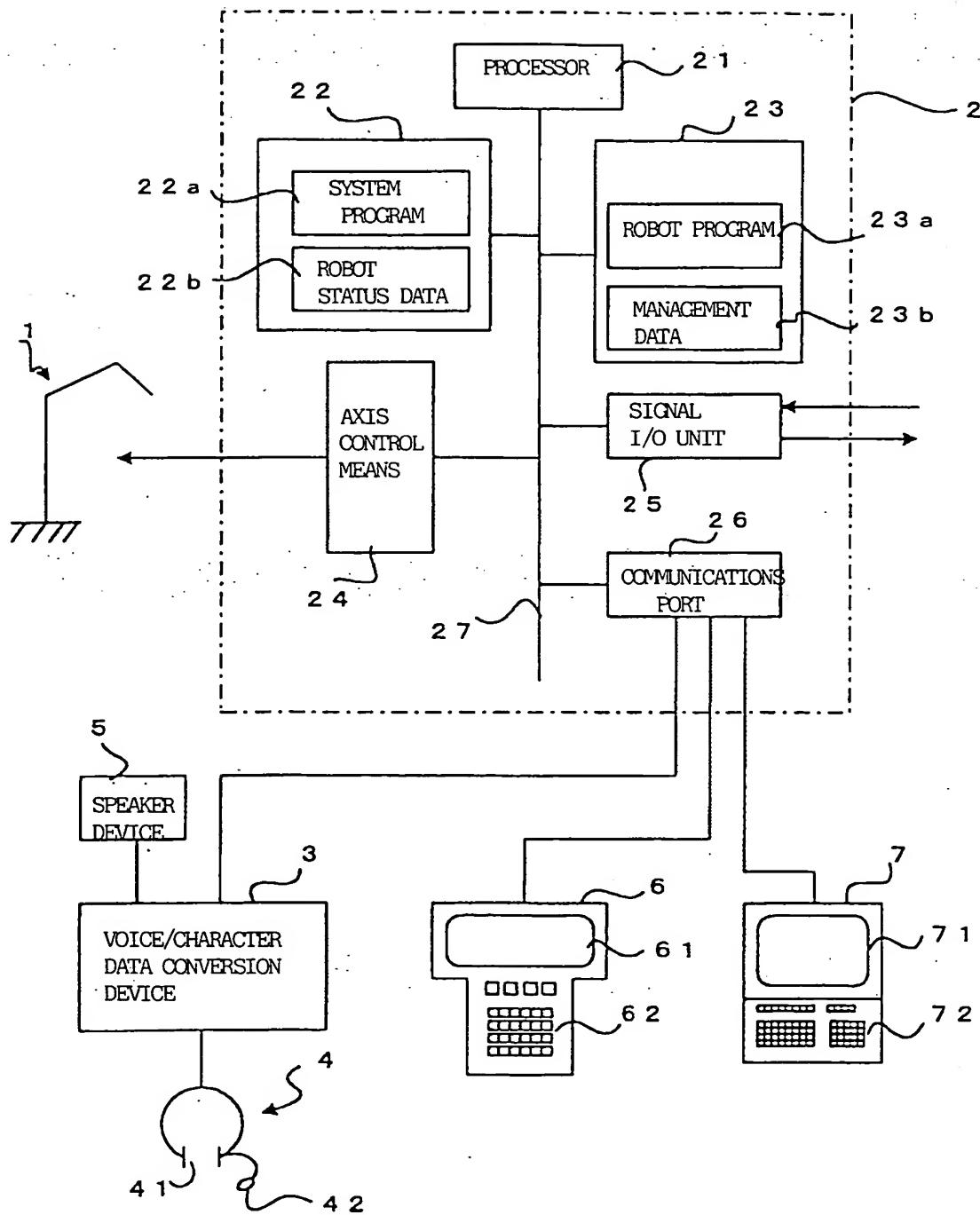


FIG. 2

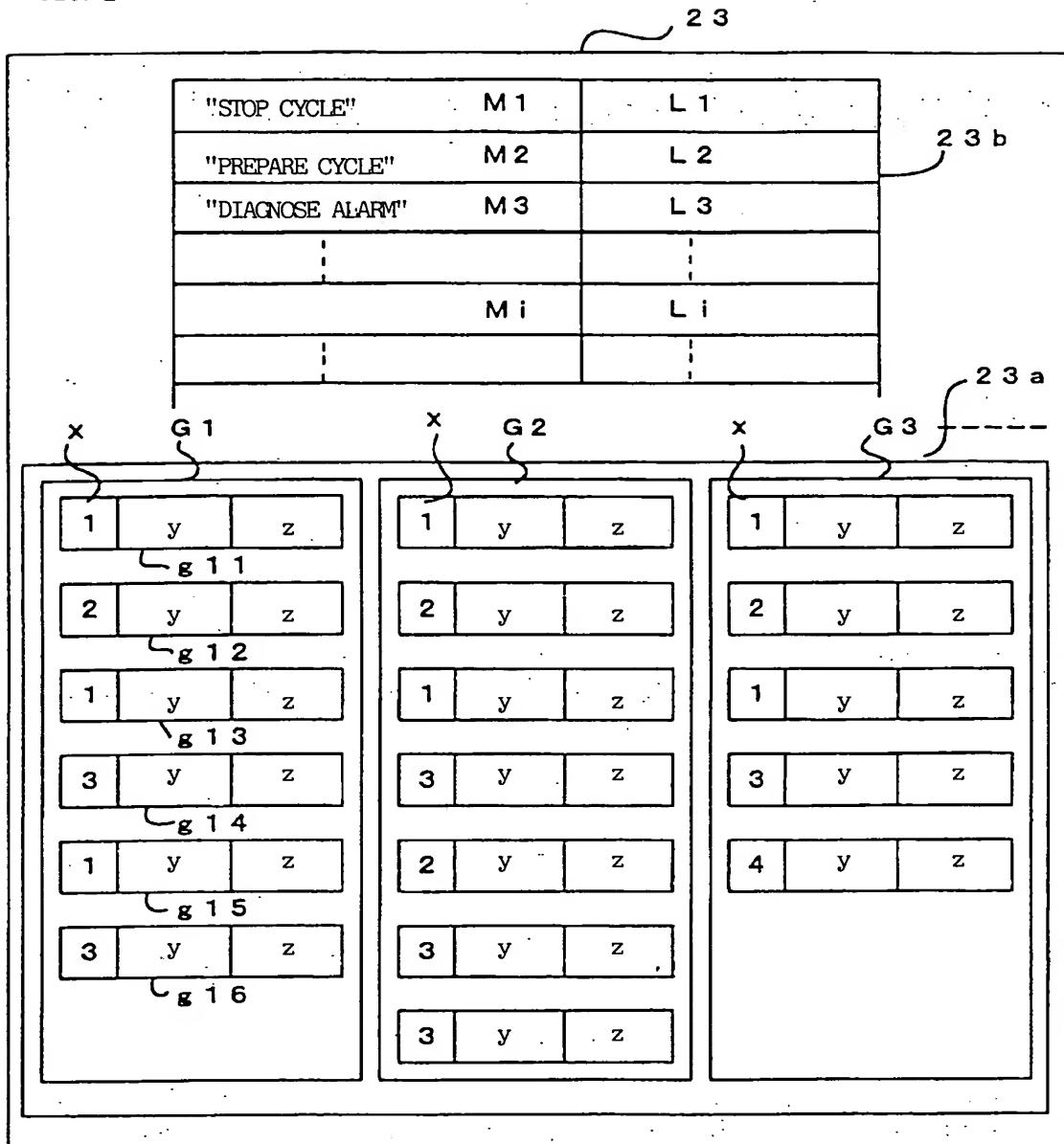


FIG. 3

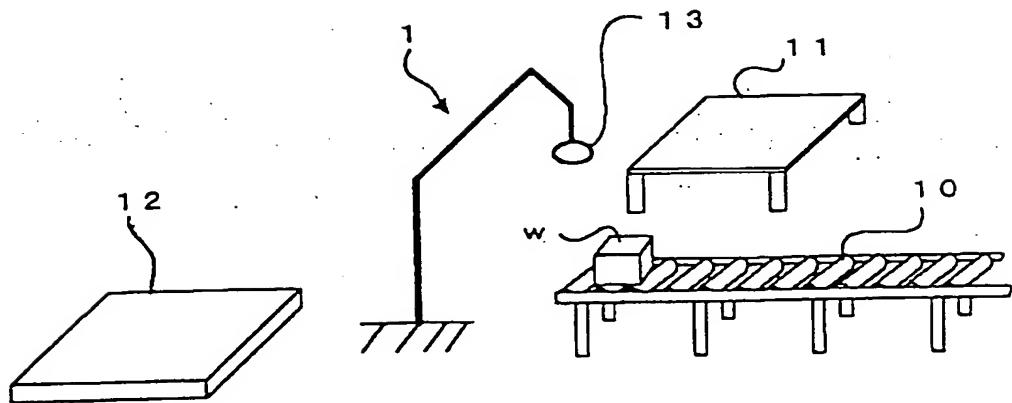


FIG. 4

1	ROBOT DOES NOT HOLD WORKPIECE	STOP ROBOT
2	LIFT WORKPIECE	LOWER AND PLACE WORKPIECE ON PROVISIONAL TABLE
2	HORIZONTALLY MOVE WORKPIECE	CONTINUE MOVING WORKPIECE AND PLACE IT ON PALLET
2	LOWER WORKPIECE	CONTINUE LOWERING WORKPIECE AND PLACE IT ON PALLET
3	HOLD WORKPIECE	RELEASE WORKPIECE AND STOP OPERATION

FIG. 5

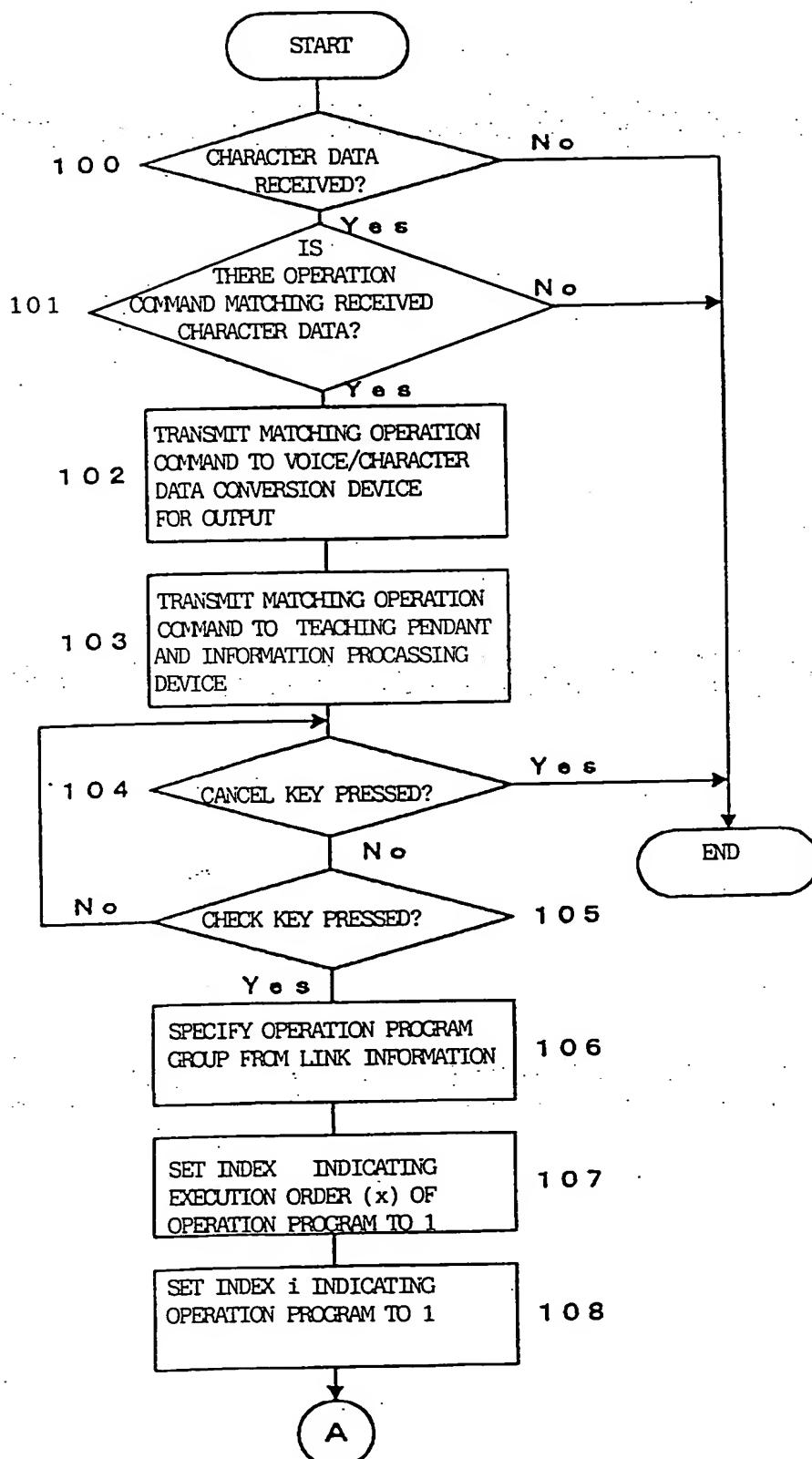


FIG. 6

